2015 SIDRA PhD School on Underwater Robotics Bertinoro, Italy, July 16-18 2015 www.automatica.it/dottorato_scuole.htm

coordinator: Gianluca Antonelli **lecturers:**

Pedro Aguiar Filippo Arrichiello Andrea Caiti Giuseppe Casalino Alessio Turetta David Scaradozzi

School objectives and program

The school has been designed with the aim to give to the PhD student a background in underwater robotics following a control perspective. The main aspects that characterize the underwater environment are presented both from the theoretical and technological aspect.

The introduction covers the current state of the art in underwater applications, how operations such as exploring or intervention are currently implemented by the industry and research centres. Then, the projects running in Europe under FP7 and H2020 funding schemes are briefly presented in order to give a bird's eye of the topics of interest under the research perspective. A quick overview of a couple of national projects is also given.

Modeling of a rigid body submerged in a fluid is presented together with the main hydrodynamic effects. The terms of interest within the operative ranges of automatic control applications will be illustrated. The mathematical model of a vehicle carrying a manipulator is then discussed. In order to better appreciate the control issues, the actuation and sensing devices are shown with the aim to appreciate their role within a feedback loop.

Given those basis, the methodological part follows a classical Navigation, Guidance and Control division. This will represent the theoretical core of the school.

The school also schedules some applicative talks concerning multiple vehicles, underwater photogrammetry and the witness of a successful university spin-off working in marine robotics.

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white methodological			
Day 1 - Thursday 16 July 2015			
9.00-10.30	Introduction		Antonelli
coffee break			
11.00-12.30	Modeling		Casalino
lunch			
15.00-16.30	Modeling		Casalino
coffee break			
17.00-18.30	A successful industrial experience		Turetta
Day 2 - Friday 17 July 2015			
9.00-10.30	Sensing & communication		Caiti
coffee break			
11.00-12.30	Navigation		Caiti
lunch			
15.00-16.30	Guidance		Aguiar
coffee break			
17.00-18.30	Control		Aguiar
Day 3 - Saturday 18 July 2015			
9.00-10.30	Multiple vehicles		Arrichiello
coffee break			
11.00-12.30	Photogrammetry		Scaradozzi

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technical/applicative content